

Your Vision, Our Future

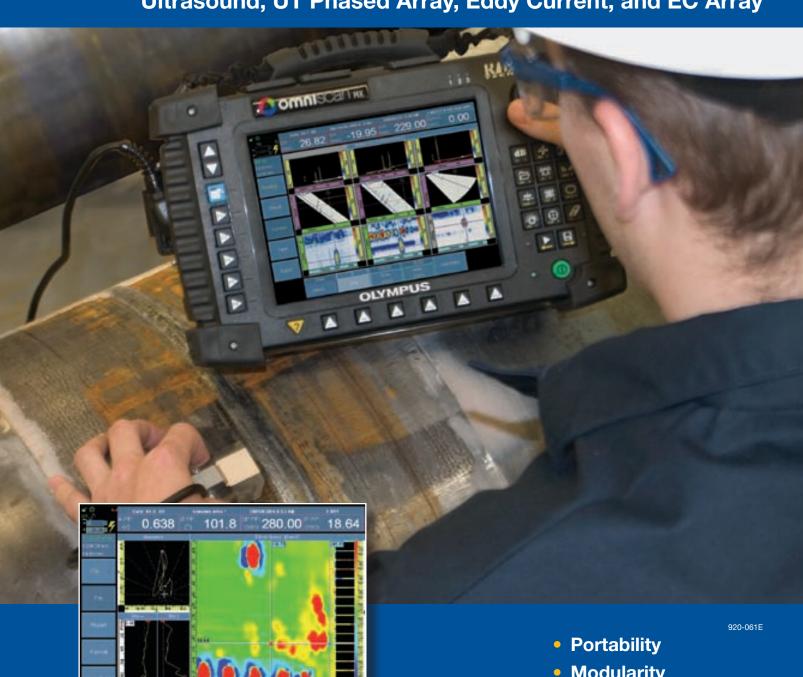
Olympus OMNIScan MX Specs Provided by www.AAATesters.com

Innovation in NDT™



OmniScan® MX

Ultrasound, UT Phased Array, Eddy Current, and EC Array



- Modularity
- Color Imaging
- Data Storage





OmniScan® MX

With hundreds of units used throughout the world, the R/D Tech OmniScan MX is Olympus NDT's most successful modular and portable phased array and eddy current array test unit. The OmniScan family includes the innovative phased array and eddy current array test units, as well as the eddy current and conventional ultrasound modules, all designed to meet the most demanding requirements of NDT. The OmniScan MX offers a high acquisition rate and powerful software features in a portable, modular mainframe to efficiently perform manual and automated inspections.

Rugged, Portable, and Battery-Operated

The OmniScan is built to work in the harshest field conditions. Its solid polycarbonate-based casing and rubber bumpers make it a rugged instrument that can withstand drops and shocks.

The OmniScan is so compact and light-weight (only 4.6 kg) that it can be carried easily and handled anywhere inside or outside. The OmniScan will run 6 hours with its two Li-ion batteries.

User Interface

The highly legible 8.4-inch real-time display (60-Hz A-scan refresh rate) with a SVGA resolution of 800 x 600 allows you to clearly see defects and details under any light conditions. A scroll knob and function keys make it easy to browse through and select functions. A mouse and a keyboard can also be plugged in for users looking for a more PC-like interface.

Modular Platform

The instrument is a modular platform that allows you to switch among its different test modules on location. The platform detects the new module and the technology supported so that the configuration and test environment are set automatically.

OmniScan Connector

The OmniScan connector has a probe ID feature that enables physical detection and recognition of the probe connected to the mainframe.

- Sets the probe to an appropriate frequency to prevent probe damage.
- Sets C-scan resolution of ECA probes.
- · Loads the correct probe parameters.





Eddy current array module

8-channel UT module

16:16M phased array module

32:128 phased array module





Adapters able to connect to probes from other manufacturers are available.

Setup and Report

- Setup storage compatible with Microsoft® Windows® (exportable using a CompactFlash® card)
- Complete report setup including reading configuration, which can be customized using HTML page layout
- On-screen interactive help that can be customized for procedure-oriented setups using HTML script templates
- Setup preview
- Predefined setups

Connectivity, Data Storage, and Imaging

The OmniScan® offers alarm outputs as well as the standard PC ports: USB, SVGA out, and Ethernet™. It offers internal data storage capability and extended storage via a CF (CompactFlash®) card slot, as well as any USB or network storage.

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Typical Applications

Girth Weld Inspection

Olympus NDT has developed a circumferential weld inspection system based on the OmniScan PA for the oil and gas industry. This phased array system is qualified to inspect tube with diameters ranging from 48 mm to 1524 mm and thicknesses from 5 mm to 25 mm in compliance with ASME Boiler and Pressure Vessel Code Section V. The semiautomated system offers better inspection speed and detection, and makes the interpretation of the indications significantly easier.



The combination of time-of-flight diffraction (TOFD) and pulse-echo techniques means that the complete inspection is done in a single scan, significantly reducing the inspection time when compared to conventional raster scanning or radiography. Inspection results are available instantaneously, allowing you to spot a problem with the welding equipment and fix it right away. Based on our vast experience in the nuclear and petrochemical industries, this system includes all the functions that are needed for code-compliant weld inspections.

Scribe Marks Inspection with No Paint Removal

The Flight Standards Information Bulletin for Airworthiness (FSAW 03-10B), issued on November 2003, report damage along fuselage skin lap joints, butt joints, and other areas of several aircraft caused by the use of sharp tools used during paint and sealant removal.

The OmniScan allows the scribe marks inspection to be done without paint removal which is a huge time saver. The inspection is done in a single pass using 60° to 85° SW sector scans. OmniScan PA is now referenced in the Boeing NTM manuals, 737 NDT Manual, Part 4, 53-30-06, July 2005.

Aircraft Fuselage Inspection

The OmniScan ECA (eddy current array) provides the ability to detect hidden corrosion and cracks in multilayer structures. Currently, material loss of 10% of the lap splice thickness can be detected in aluminum at a depth of 0.2 in. Surface and subsurface cracks can be detected in the skin, at the fastener, or at the lap joint edges.









Ultrasound Inspection

Time-of-Flight Diffraction (TOFD) Testing

TOFD is a technique that uses two probes in pitch-and-catch mode. TOFD detects and records signals diffracted from defect tips for both detection and sizing. The TOFD data is displayed in a grayscale B-scan view. TOFD offers wide coverage and amplitude-independent sizing compliant with the ASME-2235 code.

- One-line scan for full-volume inspection
- · Setup independent of weld configuration
- Very sensitive to all kinds of defects and unaffected by defect orientation

Time-of-Flight Diffraction (TOFD) and Pulse-Echo Testing

While TOFD is a very powerful and efficient technique, it suffers from limited coverage resulting from two dead inspection zones: one dead zone is near the surface, the other is at the backwall.

OmniScan UT allows inspections simultaneously combining TOFD with conventional pulse echo. Pulse echo complements TOFD and covers the dead zones.

- TOFD inspection
- 45° pulse-echo for weld cap inspection on either sides of the weld
- 60° pulse-echo for weld root inspection on either sides of the weld

O-Degree Testing (Corrosion and Composite)

The 0-degree testing measures time-offlight and amplitude of ultrasonic echoes reflecting from the part into gates in order to detect and measure defects.

- C-scan imaging
- Full A-scan recording with C-scan postprocessing

Ultrasound Transducers

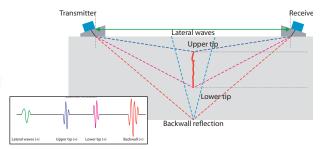
Olympus NDT offers thousands of transducers in standard frequencies, element diameters, and connector styles.

- Contact and immersion transducers
- Dual transducers
- Angle beam transducers and wedges
- Replaceable delay line transducers
- Protected-face transducers
- Normal incidence shear wave transducers

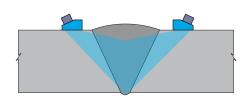


The TOFD hand scanner is small, lightweight, efficient, low-cost, and versatile weld inspection solution.

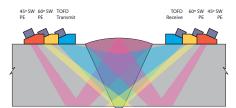
It can accommodate a full range of probes and wedges, including the CentraScan™ composite product line



General view of TOFD setup for linear weld inspection showing lateral wave, backwall echo, and diffracted signals on the A-scan.



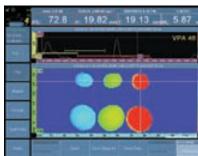
Weld inspection using TOFD.



Weld inspection using combined TOFD and pulse-echo.



HSP-XY01 scanner used for corrosion mapping applications.



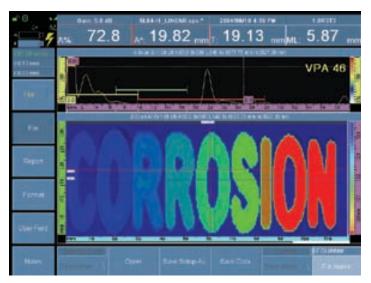
 $\hbox{\it Corrosion mapping C-scan display.}$



Ultrasound Software

Full-Featured C-Scan

- Monitors amplitude, peak position, crossing level position, and thickness on each gate
- Automatic gate synchronizes from previous gate for higher dynamic range of thickness.
- A-scan data storage and C-scan postprocessing capabilities



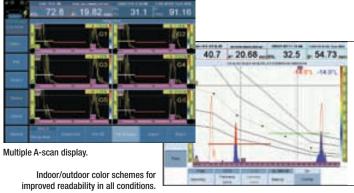
- Optional IF gate for surface following synchronization or measurement gate or TCG/DAC curves
- Either positive or negative gate on RF signal (independent for each gate)
- Eight alarms completely configurable on single gate events or multiple gate events, filter for *n* occurrences from one or multiple channels
- Customizable color palette for amplitude and thickness C-scan
- · Adjustable 256-level color palette
- 2-axis mechanical encoder with data acquisition synchronization on mechanical movement
- Optional data library to access A-scan and/or C-scan on PC for custom processing

Full-Featured B-Scan

- · Easy-to-interpret cross-sectional view of inspected part
- Excellent display of corrosion mapping of boilers, pipes, and storage tanks
- Visual identification of the thickness values acquired
- Encoded TOFD capability for amplitude-independant defect sizing

Full-Featured A-Scan

- Color-selectable A-scan display
- Reject mode
- Hollow mode
- Peak-hold mode (always keeps the signal that shows the maximum amplitude in gate A)
- Gate threshold level crossing (changes the color of the curve that is over the gate level)
- 60 Hz A-scan refresh rate with overlays of envelope and peak inside the gate

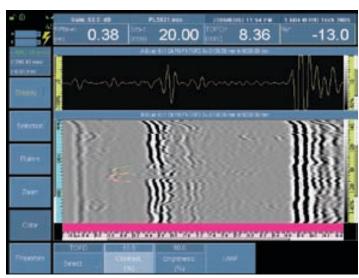


Step-by-Step calibration Wizards

All calibration procedures are guided using step-by-step wizards.

- Sound velocity calibration
- Wedge delay calibration
- TOFD calibration
- TCG calibration
- Encoder calibration

TOFD Option



- B-scan encoded data imaging and storage
- · Adjustable for brightness and contrast grayscale color palette
- 100 MHz A-scan digitizing
- TOFD calibration wizard online and offline
- · Hyperbolic cursor and reading for TOFD sizing
- · Lateral wave resynchronization

Phased Array Inspection

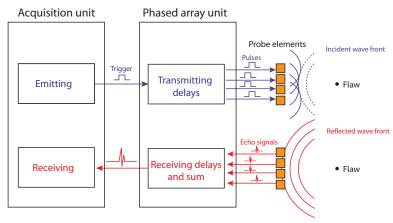
Phased Array Technology

Phased array technology generates an ultrasonic beam with the capability of setting beam parameters such as angle, focal distance, and focal point size through software. Furthermore, this beam can be multiplexed over a large array. These capabilities open a series of new possibilities. For instance, it is possible to quickly vary the angle of the beam to scan a part without moving the probe itself. Phased arrays also allow the replacement of multiple probes and even mechanical components. Inspecting a part with a variable-angle beam also maximizes detection regardless of the defect orientation, while optimizing signalto-noise ratio.

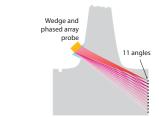
Benefits of Phased Arrays

Phased array technology offers the following capabilities:

- Software control of beam angle, focal distance, and spot size
- Multiple-angle inspection with a single, small, electronically-controlled multielement probe
- Greater flexibility for the inspection of complex geometry
- High-speed scans with no moving parts



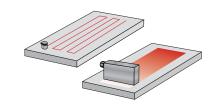
To generate a beam, the various probe elements are pulsed at slightly different times. By precisely controlling the delays between the probe elements, beams of various angles, focal distances, and focal spot sizes can be produced. The echo from the desired focal point hits the various transducer elements with a computable time shift. The signals received at each transducer element are time-shifted before being summed together.



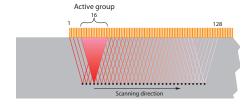
Multiple-angle inspection with one multielement probe.



Greater flexibility for the inspection of complex geometry.



The use of phased array probes enables one-line scanning and eliminates one axis of a two-axis scan.



High-speed scans with no moving parts.

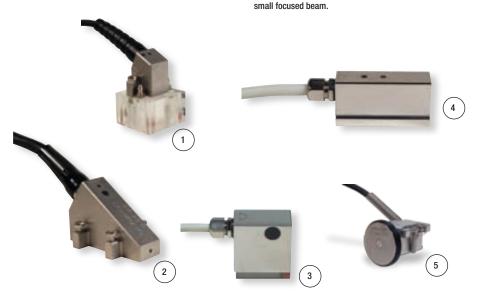
Compared to a wide, single-element transducer, phased array technology offers a much higher sensitivity due to the use of a

Phased Array Probes

R/D Tech® standard phased array transducers are divided into four categories:

- Angle beam probes with external wedges
 (1) (2)
- Angle beam probes with integrated wedge (3)
- Immersion probes (4)

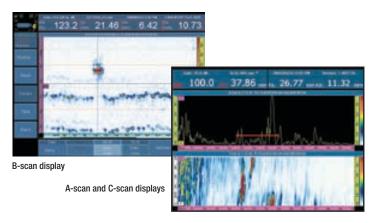
Numerous accessories, such as encoders (5) are also available.



Phased Array Software

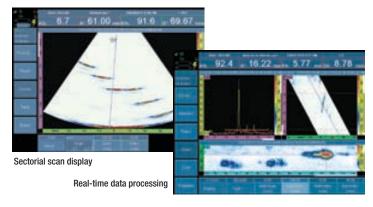
Full-Featured A-Scan, B-Scan, and C-Scans

OmniScan PA builds upon the OmniScan UT feature set and offers full-featured A-, B-, and C-scan displays.



Full-Featured Sectorial Scan

- Real-time volume-corrected representation
- Higher than 20 Hz refresh rate (up to 40 Hz)

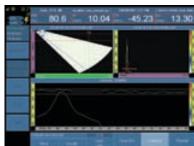


Advanced Real-Time Data Processing

- Real-time data interpolation to improve spatial representation of defects during acquisition of data
- User-selectable high- and low-pass filters to enhance A-scan and imaging quality
- Projection feature allows the operator to view vertically positioned A-scan simultaneously with sectorial scan image.

Calibration Procedures and Parameters

All calibration procedures are guided by a step-by-step menu using Next and Back navigation.



Example of sensitivity calibration

Wizards for Groups and Focal Laws

• The Group Wizard allows you to enter all probe, part, and beam parameters, and generate all focal laws in one step instead of generating them with each change.



- The step-by-step approach prevents the user from missing a parameter change.
- Online help gives general information on parameters to be set.

Multiple-Group Option

It is now possible to manage more than one probe with two different configurations: different skews, different scanning types, different inspection areas, and other parameters.

Possible Configurations for Multiple-Group Inspection

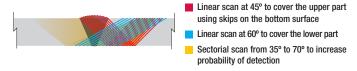
A Use one single phased array probe of 64 or more elements and create 2 different groups:



B Use one single phased array probe of 64 or 128 elements and create 2 different groups



C Use one phased array probe of 64 or 128 elements and create 3 different groups:



D Use two phased array probes of 16 or 64 elements and create 2 different groups:



- Sectorial scan from 35° to 70° for inspection from left side of the part using skips on the bottom surface
- Sectorial scan from 35° to 70° for inspection from right side of the part using skips on the bottom surface

Eddy Current Inspection

Eddy Current Technology

Eddy current (ECT) technology is a noncontact method for the inspection of metallic parts. In this technique, the probe, which is excited with an alternating current, induces eddy current in the part being inspected. Any discontinuities or material property variations that change the eddy current flow in the part are detected by the probe as a potential defect.

Over the years, probe technology and data processing have continuously progressed so that the eddy current technique is now recognized to be fast, simple, and accurate. This is why the technique is widely used in the aerospace, automotive, petrochemical, and power generation industries for the detection of surface or near-surface defects in material such as aluminum, stainless steel, copper, titanium, brass, Inconel®, and even carbon steel (surface defect only).

Benefits of Eddy Current

Eddy current offers the following capabilities:

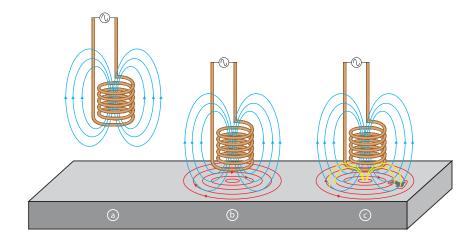
- A quick, simple, and reliable inspection technique to detect surface and near-surface defects on conductive material
- Can be used to measure electrical conductivity of the material.
- Measurement of nonconductive coating
- Hole inspection with the use of highspeed rotating scanner and surface probe

Eddy Current Probes

Olympus NDT standard eddy current probes are available in different configura-

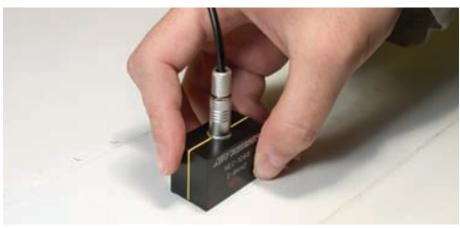
- Bolt hole probes
- Surface probes, in various shapes and configurations
- · Low-frequency Spot and Ring probes
- Sliding probes
- Wheel probes
- Conductivity probes
- Speciality probes made for specific applications

Reference standards with EDM notches can be manufactured according to the application specifications.



Probes used to perform eddy current inspections are made with a copper wire wound to form a coil. The coil shape can vary to better suit specific applications.

- a- The alternative current flowing through the coil at a chosen frequency generates a magnetic field around the coil.
- **b-** When the coil is placed close to an electrically conductive material, eddy current is induced in the material.
- **c-** If a flaw in the conductive material disturbs the eddy current circulation, the magnetic coupling with the probe is changed and a defect signal can be read by measuring the coil impedance variation.



Surface preparation is minimal. Unlike liquid penetrant or magnetic particle inspection, it is unnecessary to remove the paint from the surface to inspect the parts.



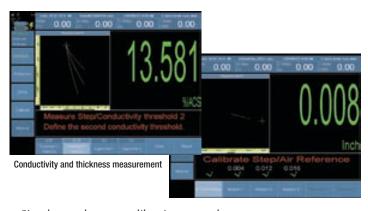
Eddy Current Software

Impedance Plane and Strip Chart Display



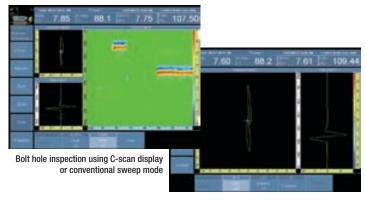
- User-selectable screen persistency
- Two-frequency operation and automatic mixing capability
- Reference signal overlay can be kept on the screen for easier signal interpretation.
- Freeze mode allows signal rotation and gain adjustment without having to hold the probe on the part.
- Zoom and Best Fit functions

Conductivity and Thickness Measurement Mode



- Simple step-by-step calibration procedure
- Material conductivity or coating thickness is displayed with very large numerals.
- Impedance plane display for signal representation during measurement
- Instruction window guides the operator during the measurement process.
- Adjustable threshold represents the measurement values in blue, green, or red.
- Measurements can be stored in a tabular report.

Rotating Probe Operation



- Impedance plane with synchronized sweep trace displayed simultaneously
- Adjustable impedance plane persistency to show one or several probe rotations on the screen
- Scrolling C-scan display to represent the inspected area in a 2-D color map
- High acquisition rate allows smooth signal representation and high-speed rotation.
- Real-time data interpolation or compression to compensate for rotation speed variation
- Full data recording capability
- Special median high-pass filter provides a stable trace.

C-Scan Surface Mapping

- Support of two encoder inputs to connect various scanners
- Real-time C-scan mapping display with impedance plane and strip chart view

Advanced Real-Time Data Processing

- Three alarms can be defined with various shapes to activate LED, buzzer, or TTL output.
- High-pass, low-pass, and specialized filters



Alarm zone in impedance plane on OmniScan ECT.

Eddy Current Array Inspection

Eddy Current Array Technology

Eddy current array (ECA) technology allows to electronically drive and read several eddy current sensors positioned side-by-side in the same probe assembly. Data acquisition is made possible through the use of multiplexing, which avoids mutual inductance between the individual sensors.

The OmniScan® ECA test configuration supports 32 sensor coils (up to 64 with an external multiplexer) working in bridge or transmit-receive mode. The operating frequency ranges from 20 Hz to 6 MHz with the option of using multiple frequencies in the same acquisition.

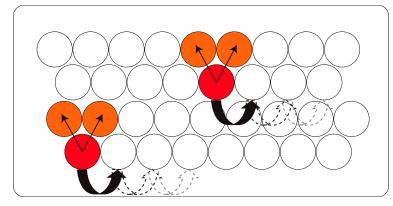
Benefits of Eddy Current Arrays

Compared to single-channel eddy current technology, eddy current array technology provides the following benefits:

- Drastically reduces inspection time.
- Covers a large area in one single pass.
- Reduces the complexity of mechanical and robotic scanning systems.
- Provides real-time cartography of the inspected region, facilitating data interpretation.
- Is well suited for complex part geometries
- Improves reliability and probability of detection (POD).

Eddy Current Array Probes

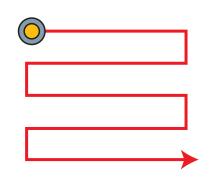
Olympus NDT manufactures R/D Tech® ECA probes for a wide range of applications. Probes can be designed to detect a specific type of flaw or to follow the shape of the part to inspect. Standard designs are available to detect defects such as cracks and pitting, and subsurface defects such as cracks in multilayer structures, as well as corrosion.

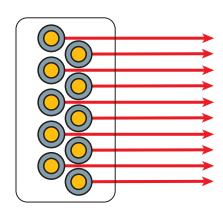


Multiplexing principle between elements.

Single coil = raster scan

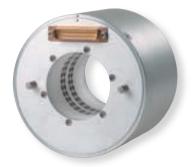
Multiple coils = one-line scan





Eddy current array probes can replace one axis of a two-axis scan and offer greater flexibility in the eddy current setup.





Probes can be made in different shapes and sizes to follow, with ease, the contour of the part to inspect.



Transmit-receive probe for corrosion detection down to 6 mm (0.125 in.) in aluminum.



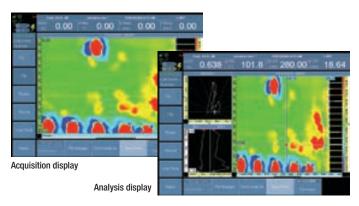
Transmit-receive probe for surface-crack detection shown with optional encoder.



Absolute probe for surface crack detection.

Eddy Current Array Software

Simple Acquisition and Analysis Displays



- Data acquisition in a C-scan view for quick and efficient defect detection
- Data selection in analysis mode to review the signal in the impedance plane and strip charts
- · Amplitude, phase, and position measurement
- Adjustable color palette
- Large impedance plane and strip chart views to accommodate conventional single-channel ECT probe inspection

Calibration Wizard



Fastener inspection using two frequencies and dual C-scan display.

- Step-by-step process
- All the channels of a group are calibrated simultaneously, each channel having its own gain and rotation.
- Amplitude and phase can be set on different reference flaws.

Alarms

- Three alarm outputs can combine LED, buzzer, and TTL output.
- Various alarm zone shapes can be defined in the impedance plane (sector, rectangular, ring, etc.).

Automatic Probe Detection and Configuration

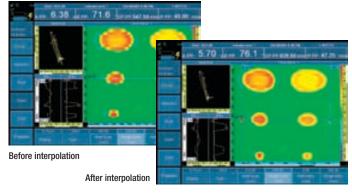
- C-scan parameters and multiplexing sequence are automatically set when the probe is connected.
- Frequency range protection to avoid probe damage

Subtraction Tools in Analysis Mode

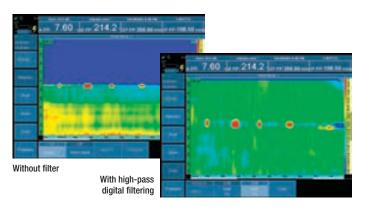
This function can be used to remove the lift-off variation that is shown between adjacent channels.

Advanced Real-Time Data Processing

• Real-time data interpolation to improve the spatial representation of the defects



- When working with two frequencies, a MIX signal can be generated to remove unwanted signals (for example, lift-off, fastener signals, etc.).
- Several filters can be applied to the data such as high-pass, low-pass, median, and averaging. The figures above represent an application where the cracks are located at the edge of a lap-joint, which has a sharp thickness variation. The filtered data may improve detection, especially for small cracks.



OmniScan Specifications

OmniScan MX Specifications

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|------------------------------|---|
| Overall dimensions | 321 mm x 209 mm x 125 mm (12.6 in. x 8.2 in. x 5 in.) |
| Weight | 4.6 kg (10.1 lb) (including module and one battery) |
| Data | storage |
| Storage devices | CompactFlash® card, most standard USB storage device, or through fast Ethernet™ Internal 32 MB DiskOnChip® |
| Data file size | 160 MB |
| | ports |
| USB ports | 3 |
| Speaker out | Yes |
| Microphone input | Yes |
| Video output | Video out (SVGA) |
| Video input | Video input (NTSC/PAL) |
| Ethernet™ | 10/100 Mb/s |
| | lines |
| Encoder | 2-axis encoder line (quadrature, |
| Lilcodei | up, down, or clock/direction) |
| Digital input | 4 digital inputs TTL, 5 V |
| Digital output | 4 digital outputs TTL, 5 V, 10 mA |
| Acquisition on/off switch | Remote acquisition enable TTL, |
| Power output line | 5 V, 500 mA power output line (short-circuit-protected) |
| Alarms | 3 TTL, 5 V, 10 mA |
| Analog output | 2 analog outputs (12 bits) ± 5 V in 10 k Ω |
| Pace input | 5 V TTL pace input |
| | play |
| Display size | 8.4 in. (diagonal) |
| Resolution | 800 x 600 pixels |
| Number of colors | 16 million |
| Type | TFT LCD |
| | supply |
| Battery type | Smart Li-ion battery |
| Number of batteries | 1 or 2 (battery chamber accommodates two hot-swappable batteries) |
| Battery life | Minimum 6 hours with two batteries; minimum of 3 hours per battery in normal operation conditions |
| DC-in voltage | 15 V – 18 V (min. 50 W) |
| Environmenta | l specifications |
| Operating temperature | 0°C to 40°C (35°C with 32:128 PA) |
| Storage temperature | –20°C to 70°C |
| Relative humidity | 0-95% non condensing. No air intake, splashproof design. |
| | |



Ultrasound Module Specifications

| Overall dimensions | 244 mm x 182 mm x 57 mm |
|--|---|
| | (9.6 in. x 7.1 in. x 2.1 in.) |
| Weight | 1 kg (2.2 lb) |
| Connectors | LEMO® 00 (2, 4, or 8) |
| Pulser | /Receiver |
| Number of pulsers/receivers | 2, 4, or 8 |
| | ulser |
| Pulse output | 50 V, 100 V, 200 V, 300 V ±10% |
| Tuise output | (variable pulse width) |
| Pulse width | Adjustable from 30 ns to 1000 ns |
| | ±10%, resolution of 2.5 ns |
| Fall time | Less than 7 ns |
| Pulse shape | Negative square wave |
| Output impedance | Less than 7 Ω |
| | ceiver |
| Receiver gain range | 0–100 dB, by steps of 0.1 dB |
| Maximum input signal | 20 V p-p (screen at 128%) |
| Minimum sensibility | 200 µV p-p (screen at 128%) |
| Noise referred to input | 160 μV p-p (36 μV RMS) (128%) |
| Input impedance | 50 Ω |
| Input filter | Centered at 1 MHz (1.5 MHz), |
| (100% bandwidth) | centered at 1 MHz (1.5 MHz), |
| (100 / 0 Dandwidth) | centered at 5 MHz (4 MHz), |
| | centered at 10 MHz (12 MHz), |
| | centered at 15 MHz, |
| | centered at 20 MHz, |
| | 0.25–2.5 MHz, 2–25 MHz BB |
| Bandwidth of the system | 0.25-32 MHz (-3 dB) |
| Rectifier | Both, positive, negative |
| Mode | PE (pulse-echo), PC (pitch-and-catch), |
| | TT (through-transmission). In P-C |
| | mode the maximum number of pulsers |
| | equals the number of channels/2 |
| Smoothing | Digital |
| | DAC |
| | |
| Number of points | 16 |
| Number of points DAC range | 16 Up to 40 dB |
| | |
| DAC range Maximum gain slope | Up to 40 dB 20 dB/µs |
| DAC range Maximum gain slope Data a | Up to 40 dB 20 dB/µs cquisition |
| DAC range Maximum gain slope Data a A-scan acquisition rate | Up to 40 dB 20 dB/µs |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging Quantity | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) rocessing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging Quantity | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post- |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging Quantity Synchronization | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) rocessing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post-synchronization) |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging Quantity Synchronization Data | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) rocessing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post-synchronization) |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging Quantity Synchronization | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post-synchronization) storage 6000 A-scans/s (512-point A-scan) |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging Quantity Synchronization Data A-scan recording (TOFD) | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post-synchronization) storage 6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate) |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging Quantity Synchronization Data | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post-synchronization) storage 6000 A-scans/s (512-point A-scan) |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging Quantity Synchronization Data A-scan recording (TOFD) | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) rocessing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post-synchronization) storage 6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate) 12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging Quantity Synchronization Data A-scan recording (TOFD) C-scan type data recording | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post-synchronization) storage 6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate) 12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz (lower frequency for corrosion mapping) |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging Quantity Synchronization Data A-scan recording (TOFD) C-scan type data recording Data vi | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post-synchronization) storage 6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate) 12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz (lower frequency for corrosion mapping) sualization |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging Quantity Synchronization Data A-scan recording (TOFD) C-scan type data recording Data vi Refresh rate | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) orcessing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post-synchronization) storage 6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate) 12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz (lower frequency for corrosion mapping) sualization 60 Hz |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging Quantity Synchronization Data A-scan recording (TOFD) C-scan type data recording Data vi Refresh rate Data syn | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post-synchronization) storage 6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate) 12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz (lower frequency for corrosion mapping) sualization 60 Hz chronization |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging Quantity Synchronization Data A-scan recording (TOFD) C-scan type data recording Data vi Refresh rate Data syn On time | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post-synchronization) storage 6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate) 12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz (lower frequency for corrosion mapping) sualization 60 Hz chronization 1 Hz–12 kHz |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging Quantity Synchronization Data A-scan recording (TOFD) C-scan type data recording Data vi Refresh rate Data syn | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post-synchronization) storage 6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate) 12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz (lower frequency for corrosion mapping) sualization 60 Hz chronization 1 Hz–12 kHz On 1 or 2 axes divided into 1 to |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging Quantity Synchronization Data A-scan recording (TOFD) C-scan type data recording Data vi Refresh rate Data syn On time On encoder | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post-synchronization) storage 6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate) 12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz (lower frequency for corrosion mapping) sualization 60 Hz chronization 1 Hz–12 kHz On 1 or 2 axes divided into 1 to 65,536 steps |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging Quantity Synchronization Data A-scan recording (TOFD) C-scan type data recording Data vi Refresh rate Data syn On time On encoder | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post-synchronization) storage 6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate) 12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz (lower frequency for corrosion mapping) sualization 60 Hz chronization 1 Hz–12 kHz On 1 or 2 axes divided into 1 to 65,536 steps arms |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging Quantity Synchronization Data A-scan recording (TOFD) C-scan type data recording Data vi Refresh rate Data syn On time On encoder A Number | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post-synchronization) storage 6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate) 12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz (lower frequency for corrosion mapping) sualization 60 Hz chronization 1 Hz–12 kHz On 1 or 2 axes divided into 1 to 65,536 steps arms 3 |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging Quantity Synchronization Data A-scan recording (TOFD) C-scan type data recording Data vi Refresh rate Data syn On time On encoder A Number Conditions | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post-synchronization) storage 6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate) 12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz (lower frequency for corrosion mapping) sualization 60 Hz chronization 1 Hz–12 kHz On 1 or 2 axes divided into 1 to 65,536 steps arms 3 Any logical combination of gates |
| DAC range Maximum gain slope Data a A-scan acquisition rate Maximum pulsing rate Data p Real-time averaging Quantity Synchronization Data A-scan recording (TOFD) C-scan type data recording Data vi Refresh rate Data syn On time On encoder A Number | Up to 40 dB 20 dB/µs cquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post-synchronization) storage 6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate) 12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz (lower frequency for corrosion mapping) sualization 60 Hz chronization 1 Hz–12 kHz On 1 or 2 axes divided into 1 to 65,536 steps arms 3 |

Eddy Current Modules Specifications

| 0 11 11 | EC Array Eddy Current |
|---|--|
| Overall dimensions | 244 mm x 182 mm x 57 mm |
| | (9.6 in. x 7.1 in. x 2.1 in.) |
| Weight | 1.2 kg (2.6 lb) |
| Connectors | 1 OmniScan® N/A |
| | connector for eddy |
| | current array probes |
| | 1 19-pin Fischer® eddy current probe |
| | 1 BNC connector |
| Number of channels | 32 channels with 4 channels |
| Number of chamiles | internal multiplexer |
| | 64 channels with |
| | external multiplexer |
| Probe recognition | Automatic probe recognition and setup |
| Generator | |
| Number of generators | 1 (with internal electronic reference) |
| Maximum voltage | 12 V p-p into 10 Ω |
| Operating frequency | 20 Hz – 6 MHz |
| Bandwidth | 8 Hz – 5 kHz (in single coil). Inversely |
| - | proportional to the time slot duration and |
| | set by the instrument in multiplexed mode |
| | Receiver |
| Number of receivers | 1 to 4 |
| Maximum input signal | 1 V p-p |
| Gain | 28–68 dB |
| In | ternal multiplexer |
| Number of generators | 32 (4 simultaneously N/A |
| Ŭ | on 8 time slots; up |
| | to 64 with external |
| | multiplexer) |
| Maximum voltage | 12 V p-p into 50 Ω |
| Number of receivers | 4 differential receivers |
| | (8 time slots each) |
| Maximum input signal | 1 V p-p |
| | Data acquisition |
| Digitizing frequency | 40 MHz 1 Hz – 15 kHz (in single coil). The rate car |
| | 1 Hz = 15 kHz (in single coil). The rate car |
| Acquisition rate | |
| Acquisition rate | be limited by the instrument's processing |
| Acquisition fate | be limited by the instrument's processing capabilities or by delays set by the |
| · | be limited by the instrument's processing capabilities or by delays set by the multiplexed excitation mode. |
| A/D resolution | be limited by the instrument's processing capabilities or by delays set by the multiplexed excitation mode. 16 bits |
| A/D resolution | be limited by the instrument's processing capabilities or by delays set by the multiplexed excitation mode. 16 bits Data processing |
| A/D resolution Phase rotation | be limited by the instrument's processing capabilities or by delays set by the multiplexed excitation mode. 16 bits Data processing 0° to 360° with increments of 0.1° |
| A/D resolution | be limited by the instrument's processing capabilities or by delays set by the multiplexed excitation mode. 16 bits Data processing 0° to 360° with increments of 0.1° FIR low-pass, FIR high-pass, FIR band- |
| A/D resolution Phase rotation | be limited by the instrument's processing capabilities or by delays set by the multiplexed excitation mode. 16 bits Data processing 0° to 360° with increments of 0.1° FIR low-pass, FIR high-pass, FIR band-pass, FIR band-stop (adjustable cutoff |
| A/D resolution Phase rotation | be limited by the instrument's processing capabilities or by delays set by the multiplexed excitation mode. 16 bits Data processing 0° to 360° with increments of 0.1° FIR low-pass, FIR high-pass, FIR band- |
| A/D resolution Phase rotation | be limited by the instrument's processing capabilities or by delays set by the multiplexed excitation mode. 16 bits Data processing 0° to 360° with increments of 0.1° FIR low-pass, FIR high-pass, FIR band-pass, FIR band-stop (adjustable cutoff frequency), median filter (variable from 2 |
| A/D resolution Phase rotation | be limited by the instrument's processing capabilities or by delays set by the multiplexed excitation mode. 16 bits Data processing 0° to 360° with increments of 0.1° FIR low-pass, FIR high-pass, FIR band-pass, FIR band-stop (adjustable cutoff frequency), median filter (variable from 2 to 200 points), mean filter (variable from 2 |
| A/D resolution Phase rotation Filtering | be limited by the instrument's processing capabilities or by delays set by the multiplexed excitation mode. 16 bits Data processing 0° to 360° with increments of 0.1° FIR low-pass, FIR high-pass, FIR band-pass, FIR band-stop (adjustable cutoff frequency), median filter (variable from 2 to 200 points), mean filter (variable from 2 to 200 points) |
| A/D resolution Phase rotation Filtering | be limited by the instrument's processing capabilities or by delays set by the multiplexed excitation mode. 16 bits Data processing 0° to 360° with increments of 0.1° FIR low-pass, FIR high-pass, FIR band-pass, FIR band-stop (adjustable cutoff frequency), median filter (variable from 2 to 200 points), mean filter (variable from 2 to 200 points) Mixing |
| A/D resolution Phase rotation Filtering Channel processing Maximum file size | be limited by the instrument's processing capabilities or by delays set by the multiplexed excitation mode. 16 bits Data processing 0° to 360° with increments of 0.1° FIR low-pass, FIR high-pass, FIR band-pass, FIR band-stop (adjustable cutoff frequency), median filter (variable from 2 to 200 points), mean filter (variable from 2 to 200 points) Mixing Data storage |
| A/D resolution Phase rotation Filtering Channel processing Maximum file size | be limited by the instrument's processing capabilities or by delays set by the multiplexed excitation mode. 16 bits Data processing 0° to 360° with increments of 0.1° FIR low-pass, FIR high-pass, FIR band-pass, FIR band-stop (adjustable cutoff frequency), median filter (variable from 2 to 200 points), mean filter (variable from 2 to 200 points) Mixing Data storage Limited by memory size |
| A/D resolution Phase rotation Filtering Channel processing Maximum file size Da | be limited by the instrument's processing capabilities or by delays set by the multiplexed excitation mode. 16 bits Data processing 0° to 360° with increments of 0.1° FIR low-pass, FIR high-pass, FIR band-pass, FIR band-stop (adjustable cutoff frequency), median filter (variable from 2 to 200 points), mean filter (variable from 2 to 200 points) Mixing Data storage Limited by memory size ta synchronization |
| A/D resolution Phase rotation Filtering Channel processing Maximum file size Da On internal clock | be limited by the instrument's processing capabilities or by delays set by the multiplexed excitation mode. 16 bits Data processing 0° to 360° with increments of 0.1° FIR low-pass, FIR high-pass, FIR band-pass, FIR band-stop (adjustable cutoff frequency), median filter (variable from 2 to 200 points), mean filter (variable from 2 to 200 points) Mixing Data storage Limited by memory size ta synchronization 1 Hz – 15 kHz (single coil) |
| A/D resolution Phase rotation Filtering Channel processing Maximum file size Da On internal clock External pace | be limited by the instrument's processing capabilities or by delays set by the multiplexed excitation mode. 16 bits Data processing 0° to 360° with increments of 0.1° FIR low-pass, FIR high-pass, FIR band-pass, FIR band-stop (adjustable cutoff frequency), median filter (variable from 2 to 200 points), mean filter (variable from 2 to 200 points) Mixing Data storage Limited by memory size ta synchronization 1 Hz – 15 kHz (single coil) Yes |
| A/D resolution Phase rotation Filtering Channel processing Maximum file size Da On internal clock External pace On encoder | be limited by the instrument's processing capabilities or by delays set by the multiplexed excitation mode. 16 bits Data processing 0° to 360° with increments of 0.1° FIR low-pass, FIR high-pass, FIR band-pass, FIR band-stop (adjustable cutoff frequency), median filter (variable from 2 to 200 points), mean filter (variable from 2 to 200 points) Mixing Data storage Limited by memory size ta synchronization 1 Hz – 15 kHz (single coil) Yes On 1 or 2 axes |
| A/D resolution Phase rotation Filtering Channel processing Maximum file size Da On internal clock External pace On encoder Number of alarms | be limited by the instrument's processing capabilities or by delays set by the multiplexed excitation mode. 16 bits Data processing 0° to 360° with increments of 0.1° FIR low-pass, FIR high-pass, FIR band-pass, FIR band-stop (adjustable cutoff frequency), median filter (variable from 2 to 200 points), mean filter (variable from 2 to 200 points) Mixing Data storage Limited by memory size ta synchronization 1 Hz – 15 kHz (single coil) Yes On 1 or 2 axes Alarms 3 |
| A/D resolution Phase rotation Filtering Channel processing Maximum file size Da On internal clock External pace On encoder | be limited by the instrument's processing capabilities or by delays set by the multiplexed excitation mode. 16 bits Data processing 0° to 360° with increments of 0.1° FIR low-pass, FIR high-pass, FIR band-pass, FIR band-stop (adjustable cutoff frequency), median filter (variable from 2 to 200 points), mean filter (variable from 2 to 200 points) Mixing Data storage Limited by memory size ta synchronization 1 Hz – 15 kHz (single coil) Yes On 1 or 2 axes Alarms 3 Pie, inverted pie, box, inverted box, and |
| A/D resolution Phase rotation Filtering Channel processing Maximum file size Da On internal clock External pace On encoder Number of alarms | be limited by the instrument's processing capabilities or by delays set by the multiplexed excitation mode. 16 bits Data processing 0° to 360° with increments of 0.1° FIR low-pass, FIR high-pass, FIR band-pass, FIR band-stop (adjustable cutoff frequency), median filter (variable from 2 to 200 points), mean filter (variable from 2 to 200 points) Mixing Data storage Limited by memory size ta synchronization 1 Hz – 15 kHz (single coil) Yes On 1 or 2 axes Alarms 3 |

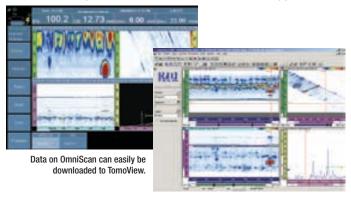
Phased Array Module Specifications

| Phased Array Module Specifications (Applies to OMNI-M-PA16128) | |
|--|--|
| · · · · · · · · · · · · · · · · · · · | 244 102 57 |
| Overall dimensions | 244 mm x 182 mm x 57 mm |
| NA7 * 1 4 | (9.6 in. x 7.1 in. x 2.1 in.) |
| Weight | 1.2 kg (2.6 lb) |
| Connectors | 1 OmniScan connector for phased-array |
| | probes |
| | 2 BNC connectors (1 pulser/receiver, |
| | 1 receiver for conventional UT) (BNC not |
| | available on models 32:32 and 32:128) |
| Number of focal laws | 256 |
| Probe recognition | Automatic probe recognition and setup |
| Pulser/Receiver | |
| Aperture | 16 elements* |
| Number of elements | 128 elements |
| | Pulser |
| Voltage | 80 V per element |
| Pulse width | Adjustable from 30 ns to 500 ns, resolution |
| i dise widiii | of 2.5 ns |
| Fall time | Less than 10 ns |
| | |
| Pulse shape | Negative square wave |
| Output impedance | Less than 25 Ω |
| | Receiver |
| Gain | 0-74 dB maximum input signal 1.32 V p-p |
| Input impedance | 75 Ω |
| System bandwidth | 0.75–18 MHz (–3 dB) |
| , | eam forming |
| Scan type | Azimuthal and linear |
| Scan quantity | |
| Active elements | Up to 8 |
| | 16* |
| Elements | 128 |
| Delay range transmission | 0–10 μs in 2.5-ns increments |
| | |
| Delay range reception | 0–10 μs in 2.5-ns increments |
| Delay range reception | ta acquisition |
| Delay range reception | |
| Delay range reception Da | ta acquisition |
| Delay range reception Da Digitizing frequency Maximum pulsing rate | ta acquisition 100 MHz (10 bits) |
| Delay range reception Da Digitizing frequency | ta acquisition 100 MHz (10 bits) Up to 10 kHz (C-scan) |
| Delay range reception Da Digitizing frequency Maximum pulsing rate | ta acquisition 100 MHz (10 bits) Up to 10 kHz (C-scan) 29 meters in steel (L-wave), 10 ms with compression. 0.24 meter in steel (L-wave), |
| Delay range reception Da Digitizing frequency Maximum pulsing rate Acquisition depth | ta acquisition 100 MHz (10 bits) Up to 10 kHz (C-scan) 29 meters in steel (L-wave), 10 ms with compression. 0.24 meter in steel (L-wave), 81.9 μs without compression |
| Delay range reception Da Digitizing frequency Maximum pulsing rate Acquisition depth | ta acquisition 100 MHz (10 bits) Up to 10 kHz (C-scan) 29 meters in steel (L-wave), 10 ms with compression. 0.24 meter in steel (L-wave), 81.9 μs without compression tta processing |
| Delay range reception Da Digitizing frequency Maximum pulsing rate Acquisition depth Da Number of data points | ta acquisition 100 MHz (10 bits) Up to 10 kHz (C-scan) 29 meters in steel (L-wave), 10 ms with compression. 0.24 meter in steel (L-wave), 81.9 µs without compression ta processing Up to 8000 |
| Delay range reception Da Digitizing frequency Maximum pulsing rate Acquisition depth Da Number of data points Real-time averaging | ta acquisition 100 MHz (10 bits) Up to 10 kHz (C-scan) 29 meters in steel (L-wave), 10 ms with compression. 0.24 meter in steel (L-wave), 81.9 μs without compression ta processing Up to 8000 2, 4, 8, 16 |
| Delay range reception Da Digitizing frequency Maximum pulsing rate Acquisition depth Da Number of data points Real-time averaging Rectifier | ta acquisition 100 MHz (10 bits) Up to 10 kHz (C-scan) 29 meters in steel (L-wave), 10 ms with compression. 0.24 meter in steel (L-wave), 81.9 μs without compression ta processing Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – |
| Delay range reception Da Digitizing frequency Maximum pulsing rate Acquisition depth Da Number of data points Real-time averaging | ta acquisition 100 MHz (10 bits) Up to 10 kHz (C-scan) 29 meters in steel (L-wave), 10 ms with compression. 0.24 meter in steel (L-wave), 81.9 μs without compression ta processing Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), |
| Delay range reception Da Digitizing frequency Maximum pulsing rate Acquisition depth Da Number of data points Real-time averaging Rectifier Filtering | ta acquisition 100 MHz (10 bits) Up to 10 kHz (C-scan) 29 meters in steel (L-wave), 10 ms with compression. 0.24 meter in steel (L-wave), 81.9 μs without compression ta processing Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) |
| Delay range reception Da Digitizing frequency Maximum pulsing rate Acquisition depth Da Number of data points Real-time averaging Rectifier | ta acquisition 100 MHz (10 bits) Up to 10 kHz (C-scan) 29 meters in steel (L-wave), 10 ms with compression. 0.24 meter in steel (L-wave), 81.9 μs without compression ta processing Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency) |
| Delay range reception Da Digitizing frequency Maximum pulsing rate Acquisition depth Da Number of data points Real-time averaging Rectifier Filtering Video filtering | ta acquisition 100 MHz (10 bits) Up to 10 kHz (C-scan) 29 meters in steel (L-wave), 10 ms with compression. 0.24 meter in steel (L-wave), 81.9 μs without compression ta processing Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency range) |
| Delay range reception Da Digitizing frequency Maximum pulsing rate Acquisition depth Da Number of data points Real-time averaging Rectifier Filtering Video filtering | ta acquisition 100 MHz (10 bits) Up to 10 kHz (C-scan) 29 meters in steel (L-wave), 10 ms with compression. 0.24 meter in steel (L-wave), 81.9 μs without compression tta processing Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency range) Data storage |
| Delay range reception Da Digitizing frequency Maximum pulsing rate Acquisition depth Da Number of data points Real-time averaging Rectifier Filtering Video filtering | ta acquisition 100 MHz (10 bits) Up to 10 kHz (C-scan) 29 meters in steel (L-wave), 10 ms with compression. 0.24 meter in steel (L-wave), 81.9 μs without compression ta processing Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency range) Data storage 6000 A-scans per second (512-point 8-bit |
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^{*} Models 16:16, 16:16M, 16:64M, 32:32 and 32:128 also available

PC-Based Analysis Software: TomoView™

OmniScan® data is compatible with R/D Tech TomoView™ PC-based software platform, or the free TomoVIEWER™ application.



- Offline analysis A, B, C, D, and sectorial scans (S-scan)
- Measurement utilities, zooming, and customizable color palette
- · Compatible with the Advanced Focal Law Calculator

Books

ADVANCED PRACTICAL NDT SERIES



The Advanced Practical NDT Series of books targets the information void between conventional UT and phased array technologies. Presently there are three titles and more on the way.

• Introduction to Phased Array Ultrasonic Technology Applications
The guideline is focused on applications, terminology, principles, useful formulas, tables, and charts.

This book is now available in Japanese.

- Phased Array Technical Guidelines: Useful Formulas, Graphics, and Examples
 This booklet gives practical hands-on examples of phased array
 - This booklet gives practical hands-on examples of phased array techniques.
- Automated Ultrasonic Testing for Pipeline Girth Welds by
 E. A. Ginzel. This 378-page book, by NDT expert Ginzel,
 provides an overview of the principles of automated ultrasonic
 testing (AUT) of girth welds, and explains the many parameters
 that influence the results of these inspections.



Olympus NDT Training Academy

Olympus NDT has organized a Training Academy with selected training companies to offer a wide variety of courses in phased arrays, applications, and related technologies. The partners in the Olympus NDT training academy are:

Davis NDE (USA)
DgzfP (Germany)
Eclipse Scientific Products (Canada)
Lavender International (UK)
TEST NDT (USA)
Vinçotte Academy (Belgium)

Courses range from a two-day long "Introduction to Phased Array" program to an in-depth two-week "Level II Phased Array" course. In both cases, students experience practical training utilizing the portable OmniScan® phased array unit.

Courses are currently being offered at training facilities in participating companies as well as at customers' determined locations worldwide. Customized courses can also be arranged. Check the latest course schedule at **www.olympusNDT.com.**

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