

Olympus OMNIScan MX Specs Provided by www.AAATesters.com

Innovation in NDT



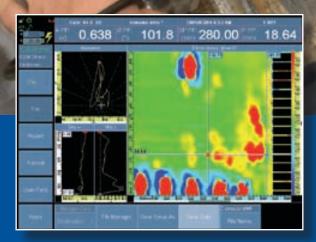
Your Vision, Our Future

OmniScan[®] MX Ultrasound, UT Phased Array, Eddy Current, and EC Array

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OLYMPUS

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920-061E

- Portability
- Modularity
- Color Imaging
- Data Storage



Innovation in NDT

OmniScan® MX

With hundreds of units used throughout the world, the R/D Tech OmniScan MX is Olympus NDT's most successful modular and portable phased array and eddy current array test unit. The OmniScan family includes the innovative phased array and eddy current array test units, as well as the eddy current and conventional ultrasound modules, all designed to meet the most demanding requirements of NDT. The OmniScan MX offers a high acquisition rate and powerful software features in a portable, modular mainframe to efficiently perform manual and automated inspections.

Rugged, Portable, and Battery-Operated

The OmniScan is built to work in the harshest field conditions. Its solid polycarbonatebased casing and rubber bumpers make it a rugged instrument that can withstand drops and shocks.

The OmniScan is so compact and lightweight (only 4.6 kg) that it can be carried easily and handled anywhere inside or outside. The OmniScan will run 6 hours with its two Li-ion batteries.

User Interface

The highly legible 8.4-inch real-time display (60-Hz A-scan refresh rate) with a SVGA resolution of 800 x 600 allows you to clearly see defects and details under any light conditions. A scroll knob and function keys make it easy to browse through and select functions. A mouse and a keyboard can also be plugged in for users looking for a more PC-like interface.

Modular Platform

The instrument is a modular platform that allows you to switch among its different test modules on location. The platform detects the new module and the technology supported so that the configuration and test environment are set automatically.

OmniScan Connector

The OmniScan connector has a probe ID feature that enables physical detection and recognition of the probe connected to the mainframe.

- Sets the probe to an appropriate frequency to prevent probe damage.
- Sets C-scan resolution of ECA probes.
- Loads the correct probe parameters.





Ethernet™ and serial ports

Eddy current array module 8-channel UT 16:16M phased array module

32:128 phased array module



module

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Adapters able to connect to probes from other manufacturers are available.

Innovation in NDT[™]

Setup and Report

- Setup storage compatible with Microsoft[®] Windows[®] (exportable using a CompactFlash[®] card)
- Complete report setup including reading configuration, which can be customized using HTML page layout
- On-screen interactive help that can be customized for procedure-oriented setups using HTML script templates
- Setup preview
- Predefined setups

Connectivity, Data Storage, and Imaging

The OmniScan[®] offers alarm outputs as well as the standard PC ports: USB, SVGA out, and Ethernet[™]. It offers internal data storage capability and extended storage via a CF (CompactFlash[®]) card slot, as well as any USB or network storage.



Girth Weld Inspection

Olympus NDT has developed a circumferential weld inspection system based on the OmniScan PA for the oil and gas industry. This phased array system is qualified to inspect tube with diameters ranging from 48 mm to 1524 mm and thicknesses from 5 mm to 25 mm in compliance with ASME Boiler and Pressure Vessel Code Section V. The semiautomated system offers better inspection speed and detection, and makes the interpretation of the indications significantly easier.

Pressure Vessel Weld Inspection

The combination of time-of-flight diffraction (TOFD) and pulse-echo techniques means that the complete inspection is done in a single scan, significantly reducing the inspection time when compared to conventional raster scanning or radiography. Inspection results are available instantaneously, allowing you to spot a problem with the welding equipment and fix it right away. Based on our vast experience in the nuclear and petrochemical industries, this system includes all the functions that are needed for code-compliant weld inspections.

Scribe Marks Inspection with No Paint Removal

The *Flight Standards Information Bulletin for Airworthiness* (FSAW 03-10B), issued on November 2003, report damage along fuselage skin lap joints, butt joints, and other areas of several aircraft caused by the use of sharp tools used during paint and sealant removal.

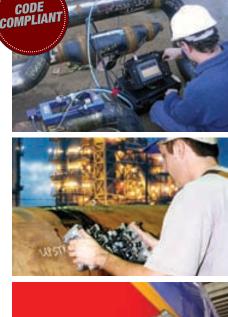
The OmniScan allows the scribe marks inspection to be done without paint removal which is a huge time saver. The inspection is done in a single pass using 60° to 85° SW sector scans. OmniScan PA is now referenced in the Boeing NTM manuals, 737 NDT Manual, Part 4, 53-30-06, July 2005.

Aircraft Fuselage Inspection

The OmniScan ECA (eddy current array) provides the ability to detect hidden corrosion and cracks in multilayer structures. Currently, material loss of 10% of the lap splice thickness can be detected in aluminum at a depth of 0.2 in. Surface and subsurface cracks can be detected in the skin, at the fastener, or at the lap joint edges.

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Ultrasound Inspection

Time-of-Flight Diffraction (TOFD) Testing

TOFD is a technique that uses two probes in pitch-and-catch mode. TOFD detects and records signals diffracted from defect tips for both detection and sizing. The TOFD data is displayed in a grayscale B-scan view. TOFD offers wide coverage and amplitudeindependent sizing compliant with the ASME-2235 code.

- One-line scan for full-volume inspection
- · Setup independent of weld configuration
- Very sensitive to all kinds of defects and unaffected by defect orientation

Time-of-Flight Diffraction (TOFD) and Pulse-Echo Testing

While TOFD is a very powerful and efficient technique, it suffers from limited coverage resulting from two dead inspection zones: one dead zone is near the surface, the other is at the backwall.

OmniScan UT allows inspections simultaneously combining TOFD with conventional pulse echo. Pulse echo complements TOFD and covers the dead zones.

- TOFD inspection
- 45° pulse-echo for weld cap inspection on either sides of the weld
- 60° pulse-echo for weld root inspection on either sides of the weld

0-Degree Testing (Corrosion and Composite)

The 0-degree testing measures time-offlight and amplitude of ultrasonic echoes reflecting from the part into gates in order to detect and measure defects.

- C-scan imaging
- Full A-scan recording with C-scan postprocessing

Ultrasound Transducers

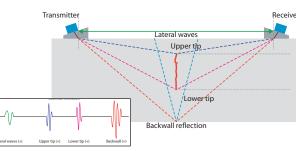
Olympus NDT offers thousands of transducers in standard frequencies, element diameters, and connector styles.

- Contact and immersion transducers
- Dual transducers
- Angle beam transducers and wedges
- Replaceable delay line transducers
- Protected-face transducers
- Normal incidence shear wave transducers

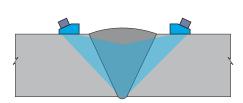


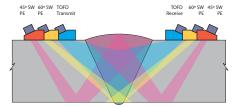
The TOFD hand scanner is small, lightweight, efficient, low-cost, and versatile weld inspection solution. It can accommodate a full range of probes and wedges, including the CentraScan™ composite product line

Weld inspection using TOFD.



General view of TOFD setup for linear weld inspection showing lateral wave, backwall echo, and diffracted signals on the A-scan.

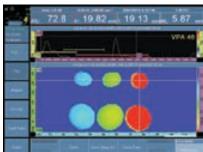




Weld inspection using combined TOFD and pulse-echo.



HSP-XY01 scanner used for corrosion mapping applications.



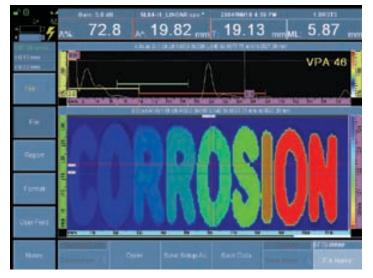
Corrosion mapping C-scan display.



Ultrasound Software

Full-Featured C-Scan

- Monitors amplitude, peak position, crossing level position, and thickness on each gate
- Automatic gate synchronizes from previous gate for higher dynamic range of thickness.
- A-scan data storage and C-scan postprocessing capabilities



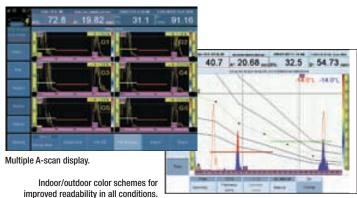
- Optional IF gate for surface following synchronization or measurement gate or TCG/DAC curves
- Either positive or negative gate on RF signal (independent for each gate)
- Eight alarms completely configurable on single gate events or multiple gate events, filter for *n* occurrences from one or multiple channels
- Customizable color palette for amplitude and thickness C-scan
- Adjustable 256-level color palette
- 2-axis mechanical encoder with data acquisition synchronization on mechanical movement
- Optional data library to access A-scan and/or C-scan on PC for custom processing

Full-Featured B-Scan

- · Easy-to-interpret cross-sectional view of inspected part
- Excellent display of corrosion mapping of boilers, pipes, and storage tanks
- Visual identification of the thickness values acquired
- Encoded TOFD capability for amplitude-independant defect sizing

Full-Featured A-Scan

- Color-selectable A-scan display
- Reject mode
- Hollow mode
- Peak-hold mode (always keeps the signal that shows the maximum amplitude in gate A)
- Gate threshold level crossing (changes the color of the curve that is over the gate level)
- 60 Hz A-scan refresh rate with overlays of envelope and peak inside the gate

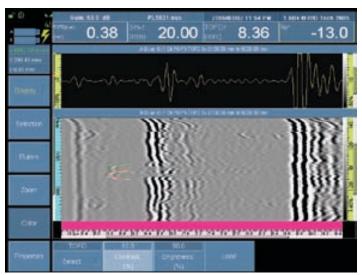


Step-by-Step calibration Wizards

All calibration procedures are guided using step-by-step wizards.

- Sound velocity calibration
- Wedge delay calibration
- TOFD calibration
- TCG calibration
- Encoder calibration

TOFD Option



- B-scan encoded data imaging and storage
- Adjustable for brightness and contrast grayscale color palette
- 100 MHz A-scan digitizing
- TOFD calibration wizard online and offline
- Hyperbolic cursor and reading for TOFD sizing
- Lateral wave resynchronization

Phased Array Inspection

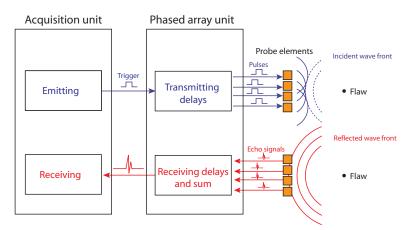
Phased Array Technology

Phased array technology generates an ultrasonic beam with the capability of setting beam parameters such as angle, focal distance, and focal point size through software. Furthermore, this beam can be multiplexed over a large array. These capabilities open a series of new possibilities. For instance, it is possible to quickly vary the angle of the beam to scan a part without moving the probe itself. Phased arrays also allow the replacement of multiple probes and even mechanical components. Inspecting a part with a variable-angle beam also maximizes detection regardless of the defect orientation, while optimizing signalto-noise ratio.

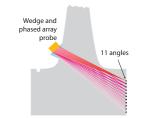
Benefits of Phased Arrays

Phased array technology offers the following capabilities:

- Software control of beam angle, focal distance, and spot size
- Multiple-angle inspection with a single, small, electronically-controlled multielement probe
- Greater flexibility for the inspection of complex geometry
- · High-speed scans with no moving parts



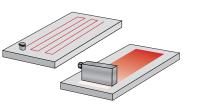
To generate a beam, the various probe elements are pulsed at slightly different times. By precisely controlling the delays between the probe elements, beams of various angles, focal distances, and focal spot sizes can be produced. The echo from the desired focal point hits the various transducer elements with a computable time shift. The signals received at each transducer element are time-shifted before being summed together.



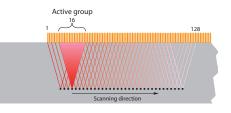
Multiple-angle inspection with one multielement probe.



Greater flexibility for the inspection of complex geometry.



The use of phased array probes enables one-line scanning and eliminates one axis of a two-axis scan.



High-speed scans with no moving parts.

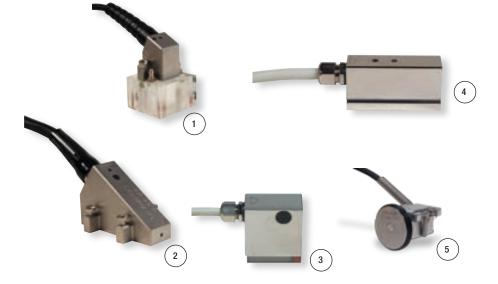
Compared to a wide, single-element transducer, phased array technology offers a much higher sensitivity due to the use of a small focused beam.

Phased Array Probes

R/D Tech[®] standard phased array transducers are divided into four categories:

- Angle beam probes with external wedges (1) (2)
- Angle beam probes with integrated wedge (3)
- Immersion probes (4)

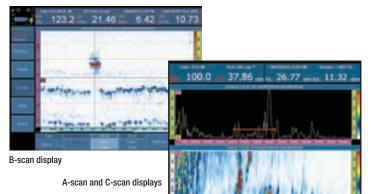
Numerous accessories, such as encoders (5) are also available.



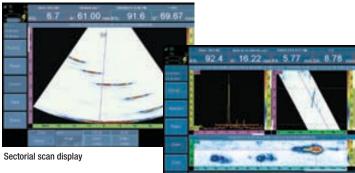
Phased Array Software

Full-Featured A-Scan, B-Scan, and C-Scans

OmniScan PA builds upon the OmniScan UT feature set and offers full-featured A-, B-, and C-scan displays.



- Full-Featured Sectorial Scan
- Real-time volume-corrected representation
- Higher than 20 Hz refresh rate (up to 40 Hz)



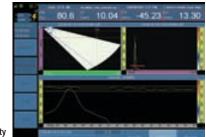
Real-time data processing

Advanced Real-Time Data Processing

- Real-time data interpolation to improve spatial representation of defects during acquisition of data
- User-selectable high- and low-pass filters to enhance A-scan and imaging quality
- Projection feature allows the operator to view vertically positioned A-scan simultaneously with sectorial scan image.

Calibration Procedures and Parameters

All calibration procedures are guided by a step-by-step menu using Next and Back navigation.



Example of sensitivity calibration

Wizards for Groups and Focal Laws

• The Group Wizard allows you to enter all probe, part, and beam parameters, and generate all focal laws in one step instead of generating them with each change.



- The step-by-step approach prevents the user from missing a parameter change.
- Online help gives general information on parameters to be set.

Multiple-Group Option

It is now possible to manage more than one probe with two different configurations: different skews, different scanning types, different inspection areas, and other parameters.

Possible Configurations for Multiple-Group Inspection

A Use one single phased array probe of 64 or more elements and create 2 different groups:



- Linear scan at 45° to cover the upper part using skips on the bottom surface
- Linear scan at 60° to cover the lower part
- B Use one single phased array probe of 64 or 128 elements and create 2 different groups

- Linear scan at 0° at low gain
- Linear scan at 0° at higher gain
- C Use one phased array probe of 64 or 128 elements and create 3 different groups:



- Linear scan at 45° to cover the upper part using skips on the bottom surface
- Linear scan at 60° to cover the lower part
 Sectorial scan from 35° to 70° to increase probability of detection
- D Use two phased array probes of 16 or 64 elements and create 2 different groups:



- Sectorial scan from 35° to 70° for inspection from left side of the part using skips on the bottom surface
- Sectorial scan from 35° to 70° for inspection from right side of the part using skips on the bottom surface

Eddy Current Inspection

Eddy Current Technology

Eddy current (ECT) technology is a noncontact method for the inspection of metallic parts. In this technique, the probe, which is excited with an alternating current, induces eddy current in the part being inspected. Any discontinuities or material property variations that change the eddy current flow in the part are detected by the probe as a potential defect.

Over the years, probe technology and data processing have continuously progressed so that the eddy current technique is now recognized to be fast, simple, and accurate. This is why the technique is widely used in the aerospace, automotive, petrochemical, and power generation industries for the detection of surface or near-surface defects in material such as aluminum, stainless steel, copper, titanium, brass, Inconel[®], and even carbon steel (surface defect only).

Benefits of Eddy Current

Eddy current offers the following capabilities:

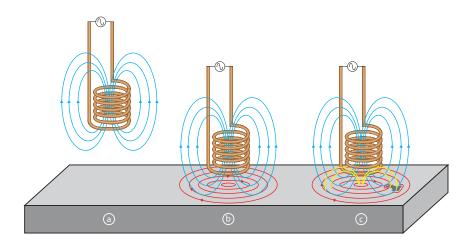
- A quick, simple, and reliable inspection technique to detect surface and near-surface defects on conductive material
- Can be used to measure electrical conductivity of the material.
- Measurement of nonconductive coating
- Hole inspection with the use of highspeed rotating scanner and surface probe

Eddy Current Probes

Olympus NDT standard eddy current probes are available in different configurations:

- Bolt hole probes
- Surface probes, in various shapes and configurations
- Low-frequency Spot and Ring probes
- Sliding probes
- Wheel probes
- Conductivity probes
- Speciality probes made for specific applications

Reference standards with EDM notches can be manufactured according to the application specifications.



Probes used to perform eddy current inspections are made with a copper wire wound to form a coil. The coil shape can vary to better suit specific applications.

- a- The alternative current flowing through the coil at a chosen frequency generates a magnetic field around the coil.
- **b** When the coil is placed close to an electrically conductive material, eddy current is induced in the material.
- c- If a flaw in the conductive material disturbs the eddy current circulation, the magnetic coupling with the probe is changed and a defect signal can be read by measuring the coil impedance variation.



Surface preparation is minimal. Unlike liquid penetrant or magnetic particle inspection, it is unnecessary to remove the paint from the surface to inspect the parts.



Eddy Current Software

Impedance Plane and Strip Chart Display



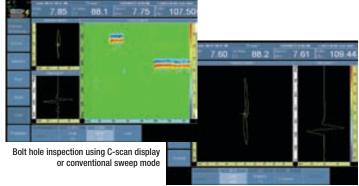
- User-selectable screen persistency
- Two-frequency operation and automatic mixing capability
- Reference signal overlay can be kept on the screen for easier signal interpretation.
- Freeze mode allows signal rotation and gain adjustment without having to hold the probe on the part.
- Zoom and Best Fit functions

Conductivity and Thickness Measurement Mode



- Simple step-by-step calibration procedure
- Material conductivity or coating thickness is displayed with very large numerals.
- Impedance plane display for signal representation during measurement
- Instruction window guides the operator during the measurement process.
- Adjustable threshold represents the measurement values in blue, green, or red.
- Measurements can be stored in a tabular report.

Rotating Probe Operation



- Impedance plane with synchronized sweep trace displayed simultaneously
- Adjustable impedance plane persistency to show one or several probe rotations on the screen
- Scrolling C-scan display to represent the inspected area in a 2-D color map
- High acquisition rate allows smooth signal representation and high-speed rotation.
- Real-time data interpolation or compression to compensate for rotation speed variation
- Full data recording capability
- Special median high-pass filter provides a stable trace.

C-Scan Surface Mapping

- Support of two encoder inputs to connect various scanners
- Real-time C-scan mapping display with impedance plane and strip chart view

Advanced Real-Time Data Processing

- Three alarms can be defined with various shapes to activate LED, buzzer, or TTL output.
- High-pass, low-pass, and specialized filters



Alarm zone in impedance plane on OmniScan ECT.

Eddy Current Array Inspection

Eddy Current Array Technology

Eddy current array (ECA) technology allows to electronically drive and read several eddy current sensors positioned side-by-side in the same probe assembly. Data acquisition is made possible through the use of multiplexing, which avoids mutual inductance between the individual sensors.

The OmniScan[®] ECA test configuration supports 32 sensor coils (up to 64 with an external multiplexer) working in bridge or transmit-receive mode. The operating frequency ranges from 20 Hz to 6 MHz with the option of using multiple frequencies in the same acquisition.

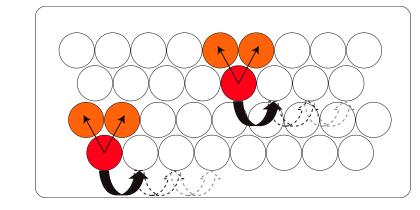
Benefits of Eddy Current Arrays

Compared to single-channel eddy current technology, eddy current array technology provides the following benefits:

- Drastically reduces inspection time.
- Covers a large area in one single pass.
- Reduces the complexity of mechanical and robotic scanning systems.
- Provides real-time cartography of the inspected region, facilitating data interpretation.
- Is well suited for complex part geometries.
- Improves reliability and probability of detection (POD).

Eddy Current Array Probes

Olympus NDT manufactures R/D Tech® ECA probes for a wide range of applications. Probes can be designed to detect a specific type of flaw or to follow the shape of the part to inspect. Standard designs are available to detect defects such as cracks and pitting, and subsurface defects such as cracks in multilayer structures, as well as corrosion.

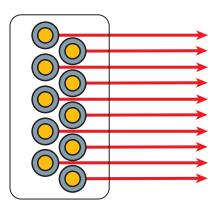


Multiplexing principle between elements.

Single coil =

raster scan

Multiple coils = one-line scan



Eddy current array probes can replace one axis of a two-axis scan and offer greater flexibility in the eddy current setup.





Probes can be made in different shapes and sizes to follow, with ease, the contour of the part to inspect.



Transmit-receive probe for corrosion detection down to 6 mm (0.125 in.) in aluminum.



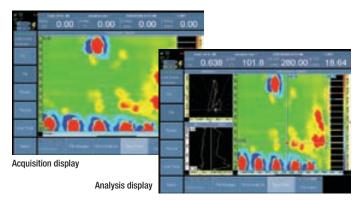
Transmit-receive probe for surface-crack detection shown with optional encoder.



Absolute probe for surface crack detection.

Eddy Current Array Software

Simple Acquisition and Analysis Displays



- Data acquisition in a C-scan view for quick and efficient defect detection
- Data selection in analysis mode to review the signal in the impedance plane and strip charts
- Amplitude, phase, and position measurement
- Adjustable color palette
- Large impedance plane and strip chart views to accommodate conventional single-channel ECT probe inspection

Calibration Wizard



Fastener inspection using two frequencies and dual C-scan display.

- Step-by-step process
- All the channels of a group are calibrated simultaneously, each channel having its own gain and rotation.
- Amplitude and phase can be set on different reference flaws.

Alarms

- Three alarm outputs can combine LED, buzzer, and TTL output.
- Various alarm zone shapes can be defined in the impedance plane (sector, rectangular, ring, etc.).

Automatic Probe Detection and Configuration

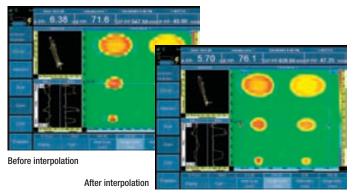
- C-scan parameters and multiplexing sequence are automatically set when the probe is connected.
- Frequency range protection to avoid probe damage

Subtraction Tools in Analysis Mode

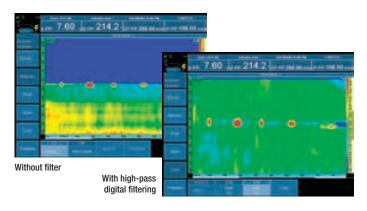
This function can be used to remove the lift-off variation that is shown between adjacent channels.

Advanced Real-Time Data Processing

• Real-time data interpolation to improve the spatial representation of the defects



- When working with two frequencies, a MIX signal can be generated to remove unwanted signals (for example, lift-off, fastener signals, etc.).
- Several filters can be applied to the data such as high-pass, low-pass, median, and averaging. The figures above represent an application where the cracks are located at the edge of a lap-joint, which has a sharp thickness variation. The filtered data may improve detection, especially for small cracks.



OmniScan Specifications

OmniScan MX Specifications

Overall dimensions	321 mm x 209 mm x 125 mm			
Weight	(12.6 in. x 8.2 in. x 5 in.) 4.6 kg (10.1 lb) (including module			
weight	and one battery)			
Data storage				
Storage devices	CompactFlash [®] card, most			
	standard USB storage device, or			
	through fast Ethernet [™]			
	Internal 32 MB DiskOnChip®			
Data file size	160 MB			
1/0	O ports			
USB ports	3			
Speaker out	Yes			
Microphone input	Yes			
Video output	Video out (SVGA)			
Video input	Video input (NTSC/PAL)			
Ethernet [™]	10/100 Mb/s			
1/0	O lines			
Encoder	2-axis encoder line (quadrature,			
	up, down, or clock/direction)			
Digital input	4 digital inputs TTL, 5 V			
Digital output	4 digital outputs TTL, 5 V, 10 mA			
Acquisition on/off switch	Remote acquisition enable TTL,			
	5 V			
Power output line	5 V, 500 mA power output line			
	(short-circuit-protected)			
Alarms	3 TTL, 5 V, 10 mA			
Analog output	2 analog outputs (12 bits) ± 5 V in			
De se la rest	10 kΩ			
Pace input	5 V TTL pace input			
	Display			
Display size Resolution	8.4 in. (diagonal)			
	800 x 600 pixels			
Number of colors	16 million TFT LCD			
Туре				
	er supply			
Battery type Number of batteries	Smart Li-ion battery			
Number of batteries	1 or 2 (battery chamber			
	accommodates two hot-swappable batteries)			
Battery life	Minimum 6 hours with two			
battery life	batteries; minimum of 3 hours			
	per battery in normal operation			
	conditions			
DC-in voltage	15 V – 18 V (min. 50 W)			
ĕ	tal specifications			
Operating temperature	0°C to 40°C (35°C with 32:128 PA)			
Storage temperature	–20°C to 70°C			
Relative humidity	0–95% non condensing. No air			
/	intake, splashproof design.			



Ultrasound Module Specifications

olirasoullu mouule specifications			
Overall dimensions	244 mm x 182 mm x 57 mm		
	(9.6 in. x 7.1 in. x 2.1 in.)		
Weight	1 kg (2.2 lb)		
Connectors	LEMO [®] 00 (2, 4, or 8)		
	r/Receiver		
Number of pulsers/receivers	2, 4, or 8		
	Pulser		
Pulse output	50 V, 100 V, 200 V, 300 V ±10%		
	(variable pulse width)		
Pulse width	Adjustable from 30 ns to 1000 ns		
	$\pm 10\%$, resolution of 2.5 ns		
Fall time	Less than 7 ns		
Pulse shape Output impedance	Negative square wave Less than 7 Ω		
	eceiver		
Receiver gain range	0–100 dB, by steps of 0.1 dB		
Maximum input signal Minimum sensibility	20 V p-p (screen at 128%) 200 μV p-p (screen at 128%)		
Noise referred to input	160 μV p-p (26 μV RMS) (128%)		
Input impedance	50 Ω		
Input filter	Centered at 1 MHz (1.5 MHz),		
(100% bandwidth)	centered at $1 \text{ MHz} (1.5 \text{ MHz})$, centered at $2 \text{ MHz} (2.25 \text{ MHz})$,		
(100 / 0 Danawidan)	centered at 5 MHz (4 MHz),		
	centered at 10 MHz (12 MHz),		
	centered at 15 MHz,		
	centered at 20 MHz,		
	0.25–2.5 MHz, 2–25 MHz BB		
Bandwidth of the system	0.25–32 MHz (–3 dB)		
Rectifier	Both, positive, negative		
Mode	PE (pulse-echo), PC (pitch-and-catch),		
	TT (through-transmission). In P-C		
	mode the maximum number of pulsers		
Smoothing	equals the number of channels/2		
Smoothing	Digital DAC		
Number of points			
Number of points	16		
DAC range	16 Up to 40 dB		
DAC range Maximum gain slope	16 Up to 40 dB 20 dB/μs		
DAC range Maximum gain slope Data	16 Up to 40 dB 20 dB/μs acquisition		
DAC range Maximum gain slope Data A-scan acquisition rate	16 Up to 40 dB 20 dB/μs acquisition 6000 A-scans/s (512-point A-scan)		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate	16 Up to 40 dB 20 dB/μs acquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan)		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data	16 Up to 40 dB 20 dB/μs acquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data Real-time averaging	16 Up to 40 dB 20 dB/μs acquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data Real-time averaging	16 Up to 40 dB 20 dB/μs acquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data Real-time averaging Quantity	16 Up to 40 dB 20 dB/µs acquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: 1 (synchro), A and B (measure)		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data Real-time averaging	16 Up to 40 dB 20 dB/μs acquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang,		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data Real-time averaging Quantity	16 Up to 40 dB 20 dB/µs acquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure)		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data Real-time averaging Quantity Synchronization	16 Up to 40 dB 20 dB/µs acquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post- synchronization)		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data Real-time averaging Quantity Synchronization	16 Up to 40 dB 20 dB/µs acquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post- synchronization) a storage		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data Real-time averaging Quantity Synchronization	16 Up to 40 dB 20 dB/µs acquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post- synchronization)		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data Real-time averaging Quantity Synchronization	16 Up to 40 dB 20 dB/µs acquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3: I (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post- synchronization) a storage 6000 A-scans/s (512-point A-scan)		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data Real-time averaging Quantity Synchronization Dat A-scan recording (TOFD)	16Up to 40 dB20 dB/µsacquisition6000 A-scans/s (512-point A-scan)1 channel at 12 kHz (C-scan)processing2, 4, 8, 16Gates3: 1 (synchro), A and B (measure)1, A, B referenced on main bang, A and B referenced on gate I (post- synchronization)a storage6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate)12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data Real-time averaging Quantity Synchronization Dat A-scan recording (TOFD) C-scan type data recording	16Up to 40 dB20 dB/µsacquisition6000 A-scans/s (512-point A-scan)1 channel at 12 kHz (C-scan)processing2, 4, 8, 16Gates3: I (synchro), A and B (measure)1, A, B referenced on main bang, A and B referenced on gate I (post- synchronization)a storage6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate)12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz (lower frequency for corrosion mapping)		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data Real-time averaging Quantity Synchronization Dat A-scan recording (TOFD) C-scan type data recording	16Up to 40 dB20 dB/µsacquisition6000 A-scans/s (512-point A-scan)1 channel at 12 kHz (C-scan)processing2, 4, 8, 16Gates3: 1 (synchro), A and B (measure)1, A, B referenced on main bang, A and B referenced on gate I (post- synchronization)a storage6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate)12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data Real-time averaging Quantity Synchronization Data A-scan recording (TOFD) C-scan type data recording Data v Refresh rate	16 Up to 40 dB 20 dB/µs acquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3:1 (synchro), A and B (measure) 1, A, B referenced on main bang, A and B referenced on gate I (post- synchronization) a storage 6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate) 12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz (lower frequency for corrosion mapping) isualization 60 Hz		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data Real-time averaging Quantity Synchronization Data A-scan recording (TOFD) C-scan type data recording Data v Refresh rate	16 Up to 40 dB 20 dB/μs acquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3:1 (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post- synchronization) a storage 6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate) 12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz (lower frequency for corrosion mapping) risualization 60 Hz chronization		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data Real-time averaging Quantity Synchronization Cascan recording (TOFD) C-scan type data recording C-scan type data recording Data v Refresh rate Data syn On time	16 Up to 40 dB 20 dB/μs acquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3:1 (synchro), A and B (measure) I, A, B referenced on main bang, A and B referenced on gate I (post- synchronization) storage 6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate) 12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz (lower frequency for corrosion mapping) tisualization 60 Hz tchronization 1 Hz-12 kHz		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data Real-time averaging Quantity Synchronization C-scan recording (TOFD) C-scan type data recording Data v Refresh rate Data syn	16 Up to 40 dB 20 dB/μs acquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3:1 (synchro), A and B (measure) 1, A, B referenced on main bang, A and B referenced on gate I (post- synchronization) a storage 6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate) 12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz (lower frequency for corrosion mapping) risualization 60 Hz therefore the substruction 1 Hz-12 kHz On 1 or 2 axes divided into 1 to		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data Real-time averaging Quantity Synchronization Cascan recording (TOFD) C-scan type data recording C-scan type data recording Data v Refresh rate Data syn On time On encoder	16Up to 40 dB20 dB/μsacquisition6000 A-scans/s (512-point A-scan)1 channel at 12 kHz (C-scan)processing2, 4, 8, 16Gates3: 1 (synchro), A and B (measure)1, A, B referenced on main bang, A and B referenced on gate I (post- synchronization)a storage6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate)12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz (lower frequency for corrosion mapping)visualization 60 Hz0 Hz1 Hz-12 kHzOn 1 or 2 axes divided into 1 to 65,536 steps		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data Real-time averaging Quantity Synchronization Caution C-scan type data recording C-scan type data recording Data v Refresh rate Data syr On time On encoder	16 Up to 40 dB 20 dB/μs acquisition 6000 A-scans/s (512-point A-scan) 1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16 Gates 3:1 (synchro), A and B (measure) 1, A, B referenced on main bang, A and B referenced on gate I (post- synchronization) a storage 6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate) 12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz (lower frequency for corrosion mapping) risualization 60 Hz therefore the substruction 1 Hz-12 kHz On 1 or 2 axes divided into 1 to		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data Real-time averaging Quantity Synchronization Data A-scan recording (TOFD) C-scan type data recording C-scan type data recording Data v Refresh rate Data syr On time On encoder A Number	16Up to 40 dB20 dB/µsacquisition6000 A-scans/s (512-point A-scan)1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16Gates3: 1 (synchro), A and B (measure)1, A, B referenced on main bang, A and B referenced on gate I (post-synchronization) a storage 6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate)12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz (lower frequency for corrosion mapping) isualization 60 Hz6 Hz chronization 1 Hz-12 kHzOn 1 or 2 axes divided into 1 to 65,536 steps3		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data Real-time averaging Quantity Synchronization Data A-scan recording (TOFD) C-scan type data recording C-scan type data recording Data v Refresh rate Data syr On time On encoder A Number Conditions	16Up to 40 dB20 dB/µsacquisition6000 A-scans/s (512-point A-scan)1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16Gates3: 1 (synchro), A and B (measure)1, A, B referenced on main bang, A and B referenced on gate I (post- synchronization) a storage 6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate)12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz (lower frequency for corrosion mapping) isualization 60 Hz60 Hz chronization 1 Hz-12 kHzOn 1 or 2 axes divided into 1 to 65,536 steps3 Any logical combination of gates		
DAC range Maximum gain slope Data A-scan acquisition rate Maximum pulsing rate Data Real-time averaging Quantity Synchronization Cascan recording (TOFD) C-scan type data recording C-scan type data recording Data v Refresh rate Data syr On time On encoder	16Up to 40 dB20 dB/µsacquisition6000 A-scans/s (512-point A-scan)1 channel at 12 kHz (C-scan) processing 2, 4, 8, 16Gates3: 1 (synchro), A and B (measure)1, A, B referenced on main bang, A and B referenced on gate I (post-synchronization) a storage 6000 A-scans/s (512-point A-scan) (3 MB/s transfer rate)12 000 (A1, A2, A3, T1, T2, T3) (3 gates) 12 kHz (lower frequency for corrosion mapping) isualization 60 Hz6 Hz chronization 1 Hz-12 kHzOn 1 or 2 axes divided into 1 to 65,536 steps3		

Eddy Current Modules Specifications

		Eddy Current	
EC ArrayEddy CurrentOverall dimensions244 mm x 182 mm x 57 mm			
Overall unitensions	244 mm x 182 mm x 57 mm (9.6 in. x 7.1 in. x 2.1 in.)		
Weight	1.2 kg (2.6 lb)		
Connectors	1 OmniScan [®]	N/A	
	connector for eddy		
	current array probes		
	1 19-pin Fischer [®] eddy o	current probe	
	connector	'	
	1 BNC connector		
Number of channels	32 channels with	4 channels	
	internal multiplexer		
	64 channels with		
	external multiplexer		
Probe recognition	Automatic probe recogn	nition and setup	
	Generator		
Number of generators	1 (with internal electron	ic reference)	
Maximum voltage	12 V p-p into 10 Ω		
Operating frequency	20 Hz – 6 MHz		
Bandwidth	8 Hz – 5 kHz (in single		
	proportional to the time		
	set by the instrument in	muluplexed mode.	
Niemilieur Carrotterre	Receiver		
Number of receivers	1 to 4		
Maximum input signal	1 V p-p		
Gain	28–68 dB		
	ternal multiplexer		
Number of generators	32 (4 simultaneously	N/A	
	on 8 time slots; up to 64 with external		
	multiplexer)		
Maximum voltage	12 V p-p into 50 Ω		
Number of receivers	4 differential receivers		
	(8 time slots each)		
Maximum input signal	1 V р-р		
	Data acquisition		
Digitizing frequency	40 MHz		
Acquisition rate	1 Hz – 15 kHz (in single	e coil). The rate can	
-	be limited by the instrur	ment's processing	
	capabilities or by delays		
	multiplexed excitation n	node.	
A/D resolution	16 bits		
	Data processing		
Phase rotation	0° to 360° with increme		
Filtering	FIR low-pass, FIR high-p	'	
	pass, FIR band-stop (adj		
	frequency), median filte		
	to 200 points), mean filt to 200 points)	ei (vanabie irom 2	
Channel processing	Mixing		
chainer processing	Data storage		
Maximum file size	Limited by memory size		
	ta synchronization		
On internal clock	1 Hz – 15 kHz (single c	oil)	
External pace	Yes	011)	
On encoder	On 1 or 2 axes		
	Alarms		
Number of alarma			
Number of alarms	3 Pio invorted pio box ir	worted have and	
Alarm zone shape	Pie, inverted pie, box, ir	iveneu box, and	
Output type	Visual, audio, and TTL s	ignals	
Output type Analog outputs	1 (X or Y)	.0	

Phased Array Module Specifications

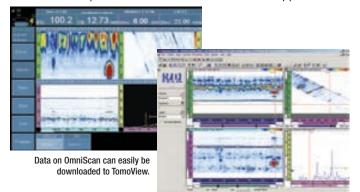
(Applies to OMNI-M-PA16128)

(Applies to OMNI-M-PA16128)		
Overall dimensions	244 mm x 182 mm x 57 mm	
	(9.6 in. x 7.1 in. x 2.1 in.)	
Weight	1.2 kg (2.6 lb)	
Connectors	1 OmniScan connector for phased-array	
	probes	
	2 BNC connectors (1 pulser/receiver,	
	1 receiver for conventional UT) (BNC not	
	available on models 32:32 and 32:128)	
Number of focal laws	256	
Probe recognition	Automatic probe recognition and setup	
Pu	Ilser/Receiver	
Aperture	16 elements*	
Number of elements	128 elements	
	Pulser	
Voltage	80 V per element	
Pulse width	Adjustable from 30 ns to 500 ns, resolution	
	of 2.5 ns	
Fall time	Less than 10 ns	
Pulse shape	Negative square wave	
Output impedance	Less than 25 Ω	
	Receiver	
Gain	0–74 dB maximum input signal 1.32 V p-p	
Input impedance	0-74 db maximum input signal 1.32 V p-p 75 Ω	
System bandwidth	0.75–18 MHz (–3 dB)	
,		
	eam forming	
Scan type	Azimuthal and linear	
Scan quantity	Up to 8	
Active elements	16*	
Elements	128	
Delay range transmission	0–10 µs in 2.5-ns increments	
Delay range reception	0–10 µs in 2.5-ns increments	
Da	ita acquisition	
Digitizing frequency	100 MHz (10 bits)	
Maximum pulsing rate	Up to 10 kHz (C-scan)	
Acquisition depth	29 meters in steel (L-wave), 10 ms with	
	compression. 0.24 meter in steel (L-wave),	
	81.9 µs without compression	
Dr		
Da	ata processing	
Number of data points	ata processing Up to 8000	
	, , , , , , , , , , , , , , , , , , ,	
Number of data points	Up to 8000	
Number of data points Real-time averaging	Up to 8000 2, 4, 8, 16	
Number of data points Real-time averaging Rectifier	Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave –	
Number of data points Real-time averaging Rectifier	Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency),	
Number of data points Real-time averaging Rectifier Filtering	Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range)	
Number of data points Real-time averaging Rectifier Filtering Video filtering	Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency	
Number of data points Real-time averaging Rectifier Filtering Video filtering	Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency range)	
Number of data points Real-time averaging Rectifier Filtering Video filtering	Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency range) Data storage	
Number of data points Real-time averaging Rectifier Filtering Video filtering	Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency range) Data storage 6000 A-scans per second (512-point 8-bit A-scan) I, A, B, up to 10 kHz (amplitude or TOF)	
Number of data points Real-time averaging Rectifier Filtering Video filtering A-scan recording (TOFD)	Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency range) Data storage 6000 A-scans per second (512-point 8-bit A-scan)	
Number of data points Real-time averaging Rectifier Filtering Video filtering A-scan recording (TOFD) C-scan type data recording Maximum file size	Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency range) Data storage 6000 A-scans per second (512-point 8-bit A-scan) I, A, B, up to 10 kHz (amplitude or TOF)	
Number of data points Real-time averaging Rectifier Filtering Video filtering A-scan recording (TOFD) C-scan type data recording Maximum file size	Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency range) Data storage 6000 A-scans per second (512-point 8-bit A-scan) I, A, B, up to 10 kHz (amplitude or TOF) Limited by memory size	
Number of data points Real-time averaging Rectifier Filtering Video filtering A-scan recording (TOFD) C-scan type data recording Maximum file size Dat	Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency range) Data storage 6000 A-scans per second (512-point 8-bit A-scan) I, A, B, up to 10 kHz (amplitude or TOF) Limited by memory size ta visualization	
Number of data points Real-time averaging Rectifier Filtering Video filtering A-scan recording (TOFD) C-scan type data recording Maximum file size Dat A-scan refresh rate Volume-corrected S-scan	Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency range) Data storage 6000 A-scans per second (512-point 8-bit A-scan) I, A, B, up to 10 kHz (amplitude or TOF) Limited by memory size ta visualization Real-time: 60 Hz Up to 40 Hz	
Number of data points Real-time averaging Rectifier Filtering Video filtering A-scan recording (TOFD) C-scan type data recording Maximum file size Data A-scan refresh rate Volume-corrected S-scan	Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency range) Data storage 6000 A-scans per second (512-point 8-bit A-scan) I, A, B, up to 10 kHz (amplitude or TOF) Limited by memory size ta visualization Real-time: 60 Hz Up to 40 Hz synchronization	
Number of data points Real-time averaging Rectifier Filtering Video filtering A-scan recording (TOFD) C-scan type data recording Maximum file size Data A-scan refresh rate Volume-corrected S-scan Data On internal clock	Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency range) Data storage 6000 A-scans per second (512-point 8-bit A-scan) I, A, B, up to 10 kHz (amplitude or TOF) Limited by memory size ta visualization Real-time: 60 Hz Up to 40 Hz synchronization 1 Hz – 10 kHz	
Number of data points Real-time averaging Rectifier Filtering Video filtering A-scan recording (TOFD) C-scan type data recording Maximum file size Data A-scan refresh rate Volume-corrected S-scan Data On internal clock On encoder	Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency range) Data storage 6000 A-scans per second (512-point 8-bit A-scan) I, A, B, up to 10 kHz (amplitude or TOF) Limited by memory size ta visualization Real-time: 60 Hz Up to 40 Hz synchronization 1 Hz – 10 kHz On 1 or 2 axes	
Number of data points Real-time averaging Rectifier Filtering Video filtering A-scan recording (TOFD) C-scan type data recording Maximum file size Dat A-scan refresh rate Volume-corrected S-scan Data On internal clock On encoder Programmable	Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency range) Data storage 6000 A-scans per second (512-point 8-bit A-scan) I, A, B, up to 10 kHz (amplitude or TOF) Limited by memory size ta visualization Real-time: 60 Hz Up to 40 Hz synchronization 1 Hz – 10 kHz On 1 or 2 axes time-corrected gain (TCG)	
Number of data points Real-time averaging Rectifier Filtering Video filtering A-scan recording (TOFD) C-scan type data recording Maximum file size Data A-scan refresh rate Volume-corrected S-scan Data On internal clock On encoder	Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency range) Data storage 6000 A-scans per second (512-point 8-bit A-scan) I, A, B, up to 10 kHz (amplitude or TOF) Limited by memory size ta visualization Real-time: 60 Hz Up to 40 Hz synchronization 1 Hz – 10 kHz On 1 or 2 axes time-corrected gain (TCG) 16 (1 TCG curve per channel for focal laws)	
Number of data points Real-time averaging Rectifier Filtering Video filtering A-scan recording (TOFD) C-scan type data recording Maximum file size Data A-scan refresh rate Volume-corrected S-scan Data On internal clock On encoder Programmable Number of points	Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency range) Data storage 6000 A-scans per second (512-point 8-bit A-scan) I, A, B, up to 10 kHz (amplitude or TOF) Limited by memory size ta visualization Real-time: 60 Hz Up to 40 Hz synchronization 1 Hz – 10 kHz On 1 or 2 axes time-corrected gain (TCG) 16 (1 TCG curve per channel for focal laws) Alarms	
Number of data points Real-time averaging Rectifier Filtering Video filtering A-scan recording (TOFD) C-scan type data recording Maximum file size Data A-scan refresh rate Volume-corrected S-scan Data On internal clock On encoder Programmable Number of points Number of alarms	Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency range) Data storage 6000 A-scans per second (512-point 8-bit A-scan) I, A, B, up to 10 kHz (amplitude or TOF) Limited by memory size ta visualization Real-time: 60 Hz Up to 40 Hz synchronization 1 Hz – 10 kHz On 1 or 2 axes time-corrected gain (TCG) 16 (1 TCG curve per channel for focal laws) Alarms 3	
Number of data points Real-time averaging Rectifier Filtering Video filtering A-scan recording (TOFD) C-scan type data recording Maximum file size Data A-scan refresh rate Volume-corrected S-scan Data On internal clock On encoder Programmable Number of points	Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency range) Data storage 6000 A-scans per second (512-point 8-bit A-scan) I, A, B, up to 10 kHz (amplitude or TOF) Limited by memory size a visualization Real-time: 60 Hz Up to 40 Hz synchronization 1 Hz – 10 kHz On 1 or 2 axes time-corrected gain (TCG) 16 (1 TCG curve per channel for focal laws) Alarms 3 Any logical combination of gates	
Number of data points Real-time averaging Rectifier Filtering Video filtering A-scan recording (TOFD) C-scan type data recording Maximum file size Data A-scan refresh rate Volume-corrected S-scan Data On internal clock On encoder Programmable Number of points Number of alarms	Up to 8000 2, 4, 8, 16 RF, full wave, halfwave +, halfwave – Low-pass (adjusted to probe frequency), digital filtering (bandwidth, frequency range) Smoothing (adjusted to probe frequency range) Data storage 6000 A-scans per second (512-point 8-bit A-scan) I, A, B, up to 10 kHz (amplitude or TOF) Limited by memory size ta visualization Real-time: 60 Hz Up to 40 Hz synchronization 1 Hz – 10 kHz On 1 or 2 axes time-corrected gain (TCG) 16 (1 TCG curve per channel for focal laws) Alarms 3	

* Models 16:16, 16:16M, 16:64M, 32:32 and 32:128 also available

PC-Based Analysis Software: TomoView[™]

OmniScan[®] data is compatible with R/D Tech TomoView[™] PCbased software platform, or the free TomoVIEWER[™] application.



- Offline analysis A, B, C, D, and sectorial scans (S-scan)
- Measurement utilities, zooming, and customizable color palette
- · Compatible with the Advanced Focal Law Calculator

Books



The Advanced Practical NDT Series of books targets the information void between conventional UT and phased array technologies. Presently there are three titles and more on the way.

- Introduction to Phased Array Ultrasonic Technology Applications The guideline is focused on applications, terminology, principles, useful formulas, tables, and charts. This book is now available in Japanese.
- Phased Array Technical Guidelines: Useful Formulas, Graphics, and Examples

This booklet gives practical hands-on examples of phased array techniques.

• Automated Ultrasonic Testing for Pipeline Girth Welds by E. A. Ginzel. This 378-page book, by NDT expert Ginzel, provides an overview of the principles of automated ultrasonic testing (AUT) of girth welds, and explains the many parameters that influence the results of these inspections.

OLYMPUS

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Olympus NDT has organized a Training Academy with selected training companies to offer a wide variety of courses in phased arrays, applications, and related technologies. The partners in the Olympus NDT training academy are:

Davis NDE (USA) DgzfP (Germany) Eclipse Scientific Products (Canada) Lavender International (UK) **TEST NDT (USA)** Vincotte Academy (Belgium)

Courses range from a two-day long "Introduction to Phased Array" program to an in-depth two-week "Level II Phased Array" course. In both cases, students experience practical training utilizing the portable OmniScan® phased array unit.

Courses are currently being offered at training facilities in participating companies as well as at customers' determined locations worldwide. Customized courses can also be arranged. Check the latest course schedule at www.olympusNDT.com.

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